

# From Sequential Testing to Optimal Stopping

Hans Rudolf Lerche

Freiburg Center for Data Analysis and Modeling (FDM)  
Department of Mathematical Stochastics  
University of Freiburg, Germany

Houston  
June 26, 2018



Larry Shepp

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

I Some Examples of Sequential Testing  
and Detection

II Overshoot and Optimality in Sequential Testing

III A Martingale-Measure Transformation Approach  
to Optimal Stopping

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# I Some Examples of Sequential Testing and Detection

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# Testing the Sign of the Drift of BM

$W_t$ ,  $t \geq 0$  Brownian motion with drift  $-\theta$  or  $+\theta$ , with  $\theta > 0$  fixed.  
 $W_0 = 0$ .

**Testing sequentially:**  $H_0 : -\theta$  versus  $H_1 : +\theta$

Prior: Uniform on  $\{-\theta, \theta\}$

$$R(T, \delta) = \frac{1}{2} (P_{-\theta}\{\delta \text{ rejects } H_0\} + c\theta^2 E_{-\theta} T) \\ + \frac{1}{2} (P_{\theta}\{\delta \text{ rejects } H_1\} + c\theta^2 E_{\theta} T)$$

Find  $(T^*, \delta^*)$  with  $R(T^*, \delta^*) = \min_{(T, \delta)} R(T, \delta)$ .

$$\delta_T^* = 1_{\{W_T > 0\}}, \quad T^* = ?$$

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

Representation of the risk:

$$R(T, \delta_T^*) = \int h(\theta | W_T |) dQ$$

with  $h(x) = \frac{e^{-2x}}{1+e^{-2x}} + cx \frac{1-e^{-2x}}{1+e^{-2x}}$  and  $Q = \frac{1}{2}P_\theta + \frac{1}{2}P_{-\theta}$

Note that  $\left. \frac{dP_\theta}{dP_{-\theta}} \right|_{\mathcal{F}_T} = \exp(2\theta W_T)$

$h$  has a unique minimum in  $a_c$  and

$$R(T, \delta_T^*) = \int h(\theta | W_T |) dQ \geq h(a_c)$$

Let  $T^* = \min\{t > 0 \mid \theta | W_t | = a_c\}$ .

Since  $Q(T^* < \infty) = 1$  it follows  $R(T^*, \delta_{T^*}^*) = h(a_c)$ .

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

# The Repeated Significance Test as Bayes Test (RST)

$W_t$ ,  $t \geq 0$  Brownian motion with drift  $\theta$ ;  $P_\theta$  underlying measure.

**Testing sequentially:**  $H_0 : \theta < 0$  versus  $H_1 : \theta > 0$

Prior:  $G = N(0, r^{-1})$

$$R(T, \delta) = \int_{-\infty}^0 (P_\theta\{\delta \text{ rejects } H_0\} + c\theta^2 E_\theta T) G(d\theta) \\ + \int_0^{\infty} (P_\theta\{\delta \text{ rejects } H_1\} + c\theta^2 E_\theta T) G(d\theta)$$

Find  $(T^*, \delta^*)$  with  $R(T^*, \delta^*) = \min_{(T, \delta)} R(T, \delta)$ .

$$\delta^* = \delta_T^* = 1_{\{W_T > 0\}} \quad T^* = ?$$

PNAS, 83 (1986)

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

Representation of the risk:

$$R(T, \delta_T^*) = \int g\left(\frac{W_T^2}{T+r}\right) dQ$$

with  $g(x) = \Phi(-\sqrt{x}) + cx$ ,  $Q = \int P_\theta G(d\theta)$ ,  $G = N(0, r^{-1})$ .

$g$  is convex with unique minimum  $b_c$  and

$$R(T, \delta_T^*) = \int g\left(\frac{W_T^2}{T+r}\right) dQ \geq g(b_c)$$

Let  $T^* = \min\{t > 0 \mid W_t^2/(t+r) = b_c\}$ .

Since  $Q\{T^* < \infty\} = 1$  it follows  $R(T^*, \delta_{T^*}^*) = g(b_c)$ .

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

## The representation:

$$G = N(0, r^{-1}), \quad Q = \int P_\theta G(d\theta), \quad G_{W(T), T} = N\left(\frac{W(T)}{T+r}, \frac{1}{T+r}\right)$$

$$\begin{aligned} \int \theta^2 E_\theta T G(d\theta) &= \int \theta^2 E_\theta (T+r) G(d\theta) - 1 \\ &= \int (T+r) \int \theta^2 G_{W(T), T}(d\theta) dQ - 1 \\ &= \int (T+r) \left( \frac{W(T)^2}{(T+r)^2} + \frac{1}{T+r} \right) dQ - 1 \\ &= \int \frac{W(T)^2}{T+r} dQ \end{aligned}$$

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

# The Disruption Problem

Shiryaev (1961) studied the following problem.

Observations:  $W_t = B_t + \theta(t - \tau)^+$  with  
 $B_t, t \geq 0$  standard Brownian motion,  
 $\theta > 0$  fixed

Filtration:  $\mathcal{F}_t = \sigma(W_s; 0 \leq s \leq t)$

Change-point:  $\tau$  random time, independent of  $B$   
with distribution  $\pi = p\delta_0 + (1 - p)F$ ,  
where  $F(t) = 1 - e^{-\lambda t}$

Risk:  $R(T) = P_\pi(T < \tau) + cE_\pi(T - \tau)^+$   
Find  $T^*$  with  $R(T^*) = \min_T R(T)$ .

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

## Theorem

Let  $\pi_t = P(\tau \leq t \mid \mathcal{F}_t)$  and  $T^* = \min\{t > 0 \mid \pi_t \geq p^*\}$ .

Here  $p^*$  is the unique solution in  $(0, 1)$  of  $G'(p) = 1$ , where  $G$  is the (finite at 0) solution of

$$\frac{\theta}{2}x^2(1-x^2)G''(x) + \lambda(1-x)G'(x) = cx.$$

Then

$$\pi_t = \frac{\varphi_t}{e^{-\lambda t} + \varphi_t}$$

where

$$\varphi_t = \frac{p}{1-p} L_t + \int_0^t \frac{L_t}{L_s} \lambda e^{-\lambda s} ds$$

with

$$L_t = \exp(\theta W_t - \theta^2 t/2).$$

$\pi_t$  is a diffusion with  $d\pi_t = \lambda(1-\pi_t)dt + \theta\pi_t(1-\pi_t)d\overline{W}_t$  where  $\overline{W}_t$  is a standard Brownian motion.

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

Itô's formula yields:

$$\begin{aligned}dG(\pi_t) &= G'(\pi_t)d\pi_t + \frac{1}{2}G''(\pi_t)(d\pi_t)^2 \\ &= G'(\pi_t) \left[ \lambda(1 - \pi_t)dt + \theta\pi_t(1 - \pi_t)d\overline{W}_t \right] \\ &\quad + \frac{1}{2}G''(\pi_t)\theta^2\pi_t^2(1 - \pi_t)^2dt\end{aligned}$$

If  $G$  satisfies the equation

$$\frac{\theta^2}{2}x^2(1 - x)^2G''(x) + \lambda(1 - x)G'(x) = cx$$

and behaves well at 0, then

$$\begin{aligned}G(\pi_t) - G(\pi_0) &= c \int_0^t \pi_s ds + c \int_0^t \theta\pi_s(1 - \pi_s)d\overline{W}_s \\ \Rightarrow E_\pi [G(\pi_T) - G(\pi_0)] &= c E_\pi \int_0^T \pi_s ds.\end{aligned}$$

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

Then one obtains

$$\begin{aligned}R(T) &= P(T < \tau) + cE(T - \tau)^+ \\ &= E_\pi \left[ (1 - \pi_T) + c \int_0^T \pi_s ds \right] \\ &= \int g(\pi_T) dP - G(p)\end{aligned}$$

with  $g(x) = (1 - x) + G(x)$

$g$  is convex with a unique minimum at  $p^*$ .

This insight opened a new direction to Bayes tests of power one for change point problems with continuous composite hypotheses.

(Dissertation of M. Beibel (1994), Diploma thesis of I. Maahs (2008))

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

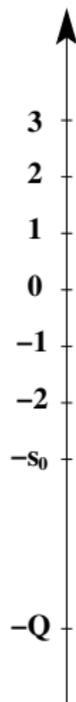
Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# A Parking Problem



$$S_0 = -Q$$

$$S_n = \sum_{i=1}^n X_i - Q$$

$X_i$  i.i.d. geometric ( $p$ )

$p$ : probability of empty spot

Park as near as possible at "0"!

Find a stopping time  $T^*$  of  $S_i, i \geq 0$  with

$$E | S_{T^*} | = \min_T E | S_T | .$$

Solution:  $T^* = \min\{n \geq 1 \mid S_n > -s_0\}$

with  $s_0 = \min\{s \in \mathbb{N} \mid 2(1-p)^s - 1 < 0\}$

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

Chow, Robbins, Siegmund (1971): Great Expectations, p. 45

# Generalized Parking Problem (GPP)

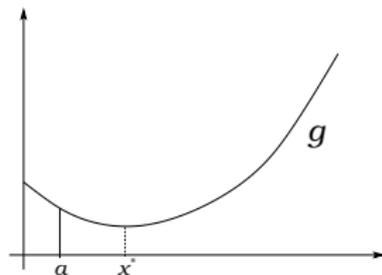
Let  $g$  be a convex nonnegative function with a unique minimum at  $x^* > 0$ .

Assume  $X_i$  i.i.d. with  $EX_i > 0$ ,

$$S_n = \sum_{i=1}^n X_i, \quad S_0 = 0.$$

Find a stopping time  $T^*$  with

$$Eg(S_{T^*}) = \min_T Eg(S_T).$$



Solution (Woodroffe–Lerche–Keener (1994)):

$$T^* = \min\{n \geq 0 \mid S_n \geq a\}$$

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

## II Overshoot and Optimality in Sequential Testing

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

**GPP**

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# Generalized Parking Problem (GPP)

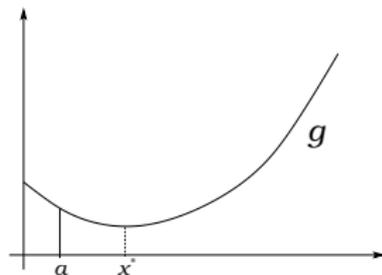
Let  $g$  be a convex nonnegative function with a unique minimum at  $b > 0$ .

Assume  $X_i$  i.i.d. with  $EX_i > 0$ ,

$$S_n = \sum_{i=1}^n X_i, \quad S_0 = 0.$$

Find a stopping time  $T^*$  with

$$Eg(S_{T^*}) = \min_T Eg(S_T).$$



Solution (Woodroffe–Lerche–Keener (1994)):

$$T^* = \min\{n \geq 0 \mid S_n \geq a\}$$

with  $a = \sup\{x \mid H^+g(x) < g(x)\}$  where  $H^+$  is the ladder-height

distribution of  $S_n$ ;  $n \geq 1$  and  $H^+g(x) = \int g(x+y)H^+(dy)$ .

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

Let  $K(z) = \int_0^z \frac{1 - H^+(y)}{\nu_1} dy$  with  $\nu_i = \int y^i dH^+(y)$ ,  $i \in \mathbb{N}$ .

$K$  is the asymptotic overshoot distribution function.

See Siegmund, *Sequential Analysis* (1985).

## Theorem 1

If  $K g(x) < \infty$  for all  $0 \leq x < \infty$ , then  $K g(x)$  is minimized at  $x = a$ .

### Example 1:

If  $g(x) = |x - b|$  for  $x \in \mathbb{R} \Rightarrow a = b - \text{med } K$ .

### Example 2:

If  $g(x) = (x - b)^2$  for  $x \in \mathbb{R}$  and  $\nu_2$  is finite  $\Rightarrow a = b - \frac{\nu_2}{\nu_1}$

### Example 3:

If  $g(x) = e^{-x} + cx$  for  $x \in \mathbb{R}$ , with  $0 < c < 1$

$\Rightarrow b = \log(\frac{1}{c})$ .

If  $\int x^2 H^+(dx) < \infty$  and if  $\kappa := \int_0^\infty e^{-x} K(dx)$

$\Rightarrow K g(x) = \kappa e^{-x} + c(x + \frac{\nu_2}{2\nu_1})$  and is minimized at  $\log(\frac{\kappa}{c}) = b - \log(\frac{1}{\kappa})$ .

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# Lorden's Result on the one-sided SPRT

Let  $P_0 \neq P_1$  be equivalent and let  $I = E_1 \log \frac{dP_1}{dP_0}(X)$ .

Minimize  $R(T) = P_0(T < \infty) + c I E_1 T$ .

Let  $\ell_n = \log \frac{dP_1^n}{dP_0^n}$ .

Then by Wald's identities

$$R(T) = \int e^{-\ell_T} dP_1 + c \int \ell_T dP_1 = \int g(\ell_T) dP_1 \quad \text{with } g(x) = e^{-x} + cx.$$

$g$  is a nonnegative convex function with a unique minimum at  $\log \frac{1}{c}$ .

Then  $T_c^* = \min\{n \geq 1 | \ell_n \geq \log(\frac{\kappa}{c})\}$  where  $\kappa = \lim_{a \rightarrow \infty} E_1 \exp(-(\ell_{\tau_a} - a))$

and  $\tau_a = \min\{n \geq 1 | \ell_n \geq a\}$ .

Then  $R(T_c^*) = c \left[ \left(1 + \log \frac{1}{c}\right) + \log \kappa + \frac{\nu_2}{2\nu_1} \right]$ .

Lorden (AS 1977)

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# Testing the Sign of the Mean with $|\theta|$ known

$S_n$ ,  $n \geq 0$  normal random walk ( $\sigma^2 = 1$ ) with mean  $-\theta$  or  $+\theta$  and with  $\theta > 0$  known,  $S_0 = 0$ .

**Testing sequentially:**  $H_0 : -\theta$  versus  $H_1 : +\theta$ .

Prior: Uniform on  $\{-\theta, \theta\}$

$$R(T, \delta) = \frac{1}{2} (P_{-\theta}\{\delta \text{ rejects } H_0\} + c\theta^2 E_{-\theta} T) \\ + \frac{1}{2} (P_{\theta}\{\delta \text{ rejects } H_1\} + c\theta^2 E_{\theta} T)$$

Let  $R_c^* = \min_{(T, \delta)} R_c(T, \delta)$ .

Let  $\delta_T^* = \mathbf{1}_{\{S_T > 0\}}$ .

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

Then

$$R_c(T, \delta^*) = \int g_c(\theta |S_T|) dQ$$

where  $g_c(x) = \frac{e^{-2x}}{1+e^{-2x}} + c x \frac{1-e^{-2x}}{1+e^{-2x}}$  and  $Q = \frac{1}{2}P_\theta + \frac{1}{2}P_{-\theta}$ .

Let  $a_c = \arg \min_x g_c(x)$  and

let  $T_c = \min \left\{ n \geq 1 \mid \theta |S_n| \geq a_c - \log \left( \frac{1}{\kappa} \right) \right\}$

with  $\kappa = \lim_{a \rightarrow \infty} E_\theta e^{-(\theta S_{\tau_a} - a)}$ .

Then it holds

$$R_c(T_c, \delta_{T_c}^*) - R_c^* = o(c) \quad \text{as } c \rightarrow 0.$$

Lorden (1977), AS

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# Nonlinear Parking Problem: Discrete Case

$Z_1, Z_2, \dots$  a perturbed random walk, say

$$Z_n = \tilde{S}_n + \xi_n \quad \text{for } n = 0, 1, 2, \dots,$$

where

$$S_n = \sum_{i=1}^n X_i, \quad n \geq 1$$

with

$$X_1, X_2, \dots \text{ i.i.d. and } 0 < EX_1 < \infty,$$

having a non-arithmetic distribution.

$\xi_n$  are slowly changing in the sense of “Woodroffe, SIAM, 1982” or Siegmund (1985).

Let  $g_c$ ,  $0 < c \leq 1$  denote convex functions. Find  $T_c^*$  with

$$Eg_c(Z_{T_c^*}) = \min_T Eg_c(Z_T).$$

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

## Definition

A sequence of random variables  $(\xi_n, n \geq 1)$  is called slowly changing if:

$$\text{i) } \limsup_{\delta \downarrow 0} \sup_{n \geq 1} P \left( \max_{0 \leq k \leq n\delta} |\xi_{n+k} - \xi_n| > \varepsilon \right) = 0 \quad \forall \varepsilon > 0$$

$$\text{ii) } \frac{1}{n} \max(|\xi_1|, |\xi_2|, \dots, |\xi_n|) \xrightarrow{P} 0$$

**Example (RST)**

$$Z_n = \frac{S_n^2}{n+r}$$
$$\tilde{S}_n = 2 \left( \theta S_n - \frac{n}{2} \theta^2 \right)$$
$$\xi_n = \frac{(S_n - n\theta)^2}{r+n} - \frac{2(S_n - n\theta)r\theta}{r+n} - \frac{nr\theta^2}{r+n}$$

$\xi_n, n > 1$  is slowly changing.

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

# Overshoot for a Perturbed Random Walk

## Theorem 2

Let  $Z_n = \tilde{S}_n + \xi_n$ , where  $\tilde{S}_n$  is a random walk with mean  $\mu > 0$ .

Let  $\xi_n$ ;  $n \geq 1$  be slowly changing.

Let  $T_a = \min\{n \geq 1 \mid Z_n \geq a\}$  and  $\tau_a = \min\{n \geq 1 \mid \tilde{S}_n \geq a\}$ .

Then

$$\lim_{a \rightarrow \infty} P_\mu(Z_{T_a} - a \leq x) = \lim_{a \rightarrow \infty} P_\mu(\tilde{S}_{\tau_a} - a \leq x)$$

Lai–Siegmund (1977)

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

For each  $0 < c \leq 1$  let  $g_c$  be a convex function with a unique minimum at  $b = b_c \geq 0$ . Assume  $\lim_{c \downarrow 0} b_c = \infty$  and there exists a convex function  $h : \mathbb{R} \rightarrow \mathbb{R}$  with minimum at zero and with

$$h_c(x) := \frac{g_c(b+x) - g_c(b)}{c} \rightarrow h(x) < \infty.$$

Let  $K(y) = \int_0^y \frac{1 - H(x)^+}{\gamma_1} dx$  for  $\tilde{S}_n$ ;  $n \geq 1$  as in the GPP.

### Theorem 3 (Schwarz, Keener-L-Woodroffe)

Let  $\gamma = \underset{x}{\operatorname{argmin}} Kh(-x)$  and  $T_{b-\gamma} = \min\{n \geq 1 \mid Z_n \geq b - \gamma\}$ .

Then as  $c \rightarrow 0$

$$1) \inf_T E g_c(Z_T) = g_c(b) + c \inf_T E h(Z_T - b) + o(c).$$

$$2) \inf_T E h(Z_T - b) = E h(Z_{T_{b-\gamma}}) + o(1)$$

$$3) E h(Z_{T_{b-\gamma}}) = Kh(-\gamma) + o(1).$$

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

## Corollary

$$\begin{aligned}\inf_T Eg_c(Z_T) &= Eg_c(Z_{T_{b-\gamma}}) \\ &= g_c(b_c) + cKh(-\gamma) + o(c)\end{aligned}$$

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

**Generalized Parking  
Problem (GPP)**

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# Testing the Mean sequentially

$S_n$ ,  $n \geq 0$  normal random walk with mean  $\theta$  and variance 1,  $S_0 = 0$ .

**Testing sequentially:**  $H_0 : \theta = 0$  versus  $H_1 : \theta \neq 0$ .

Let  $I(\theta) = E_\theta \log \frac{dP_\theta}{dP_0}(X_1)$ ,  $G = N(0, r^{-1})$

$$R_c(T) = P_0(T < \infty) + c \int I(\theta) E_\theta T G(d\theta)$$

$$\text{Let } P_* = \int P_\theta G(d\theta) \text{ and } Z_n = \log \frac{dP_*^n}{dP_0^n} = \frac{S_n^2}{2(n+r)} - \frac{1}{2} \log \left( \frac{n+r}{r} \right)$$

Then

$$R_c(T) = E_* g_c(Z_T) + E_* \log \left( \frac{T+r}{r} \right)$$

with  $g_c(z) = e^{-z} + cz$ .

$g_c$  is convex with minimum at  $b_c = \log(1/c)$ .

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

Then by Theorem 3

$$\begin{aligned} E_* g_c(Z_T) &= \int E_\theta g_c(Z_T) G(d\theta) \\ &\geq g_c(b_c) + c \left( \int_{-\infty}^{\infty} \inf_T E_\theta h(Z_T - b_c) G(d\theta) + o(1) \right) \end{aligned}$$

with  $h(z) = z + e^{-z} - 1$ .

$Z_n = \tilde{S}_n + \xi_n$  where  $\tilde{S}_n = \theta S_n - \frac{1}{2}\theta^2 n$  and  $\xi_n$  is slowly changing.

Then by Theorem 3 again

$$\inf_T E_\theta h(Z_T - b_c) \geq K^\theta h(-\gamma(\theta)) + o(1)$$

Here  $K^\theta$  is the asymptotic overshoot distribution of  $\tilde{S}_n$ .

$\gamma(\theta) = \log(1/\kappa(\theta))$  where  $\kappa(\theta) = \int e^{-x} K^\theta(dx)$ .

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

Then

$$\begin{aligned}\inf_T E_* g(Z_T) &\geq g_c(b_c) + c \left( \int_{-\infty}^{\infty} K^\theta h(-\gamma(\theta)) G(d\theta) + o(1) \right) \\ &= g_c(b_c) + c \left( \int_{-\infty}^{\infty} \left( \kappa(\theta) + \frac{\nu_2(\theta)}{2\nu_1(\theta)} - 1 \right) G(d\theta) + o(1) \right)\end{aligned}$$

One can show:

$$T_c = \inf\{n \geq 1 \mid Z_n > b_c - \Gamma_n\}, \quad \text{where } \Gamma_n = E[\gamma(\theta) \mid Y_1, \dots, Y_n],$$

assumes this lower bound.

G. Schwarz (1993)

Note: The repeated significance test does not satisfy the assumptions of Theorem 3. In his case a stabilizing  $h$  does not exist.

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

**Testing the Mean  
sequentially**

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# III A Martingale-Measure Transformation

## Approach to Optimal Stopping

# The Basic Idea: OS as GPP

Let  $(Z_t, \mathcal{F}_t; t \geq 0)$  denote a continuous stochastic process on a probability space  $(\Omega, \mathcal{F}, P)$ .

Find a stopping time  $T^*$  with

$$E_P (Z_{T^*} 1_{\{T^* < \infty\}}) = \max_T E_P (Z_T 1_{\{T < \infty\}}).$$

**Idea:** (Beibel-Lerche (1997))

Find a process  $(X_t, \mathcal{F}_t; t \geq 0)$ , a nonnegative martingale  $(M_t, \mathcal{F}_t; t \geq 0)$  with  $E_P M_0 = 1$  and a function  $f$  with unique maximum at  $x^*$  such that  $Z_t = f(X_t)M_t$ .

Then

$$\begin{aligned} E_P Z_{T^*} 1_{\{T^* < \infty\}} &= E_P (f(X_{T^*})M_{T^*} 1_{\{T^* < \infty\}}) \\ &\leq f(x^*) E_P M_{T^*} 1_{\{T^* < \infty\}} \\ &\leq f(x^*) \end{aligned}$$

With  $T^* = \min\{t \geq 0 \mid X_t = x^*\}$  the inequalities become equalities, if  $E_P M_{T^*} 1_{\{T^* < \infty\}} = 1$ .

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

# Optimality of Parabolic Boundaries

Let  $X_t = B_t + x_0$ ,  $t \geq 0$  with  $B_t$  standard Brownian motion. For a measurable function  $g$  find a stopping time  $T$  that maximizes

$$E_p \left( (T + 1)^{-\beta} g \left( \frac{X_T}{\sqrt{T + 1}} \right) \right). \quad (\text{Moerbeke (1974)})$$

$$\text{Let } H(x) = \int_0^\infty e^{ux - u^2/2} u^{2\beta - 1} du \text{ with } \beta > 0$$

and assume that there exists a unique point  $x^*$  with

$$\sup_{x \in \mathbb{R}} \frac{g(x)}{H(x)} = \frac{g(x^*)}{H(x^*)} = C^* \quad \text{and } 0 < C^* < \infty$$

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

**Parabolic Boundaries**

Put Option

Two-Sided Boundaries

Stopping of Diffusions

$$(t+1)^{-\beta} H\left(\frac{X_t}{\sqrt{t+1}}\right) = \int_0^\infty e^{uX_t - \frac{u^2}{2}t} \left(e^{-\frac{u^2}{2}} u^{2\beta-1}\right) du$$

is a positive martingale with starting value  $H(x_0)$ .

Thus  $M_t = (t+1)^{-\beta} H\left(\frac{X_t}{\sqrt{t+1}}\right) / H(x_0)$  is a positive martingale with  $E_p M_0 = 1$ .

Then

$$E_p \left( (T+1)^{-\beta} g\left(\frac{X_T}{\sqrt{T+1}}\right) \right) = H(x_0) E_p \frac{g\left(\frac{X_T}{\sqrt{T+1}}\right)}{H\left(\frac{X_T}{\sqrt{T+1}}\right)} M_T$$

$$\leq H(x_0) C^*.$$

Let  $T^* = \inf \left\{ t > 0 \mid \frac{X_t}{\sqrt{t+1}} = x^* \right\}$ .

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

For  $x_0 < x^*$  we have  $E_p M_{T^*} = 1$ . Thus

$$\begin{aligned} \sup_T E_p \left\{ (T+1)^{-\beta} g \left( \frac{X_T}{\sqrt{T+1}} \right) \right\} &= E_p \left\{ (T^*+1)^{-\beta} g \left( \frac{X_{T^*}}{\sqrt{T^*+1}} \right) \right\} \\ &= H(x_0) C^* \end{aligned}$$

**Special case:**

$$g(x) = x, \quad x_0 = 0, \quad \beta = \frac{1}{2}$$

$$E_p(X_T/(T+1)) = \max \text{ with}$$

$$T^* = \min \left\{ t > 0 \mid \frac{X_t}{\sqrt{t+1}} = x^* \right\}$$

$$x^* \text{ is solution of } x = (1-x^2) \int_0^\infty e^{ux-u^2/2} du. \quad \text{Shepp (AMS 1969)}$$

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# Perpetual American Put Option

Samuelson (1965), McKean (1965)

$X_t = \sigma B_t + \mu t$ ,  $t \geq 0$  Brownian motion with drift  $\mu$  and variance  $\sigma^2$ .

Find a stopping time  $T^*$  which maximizes

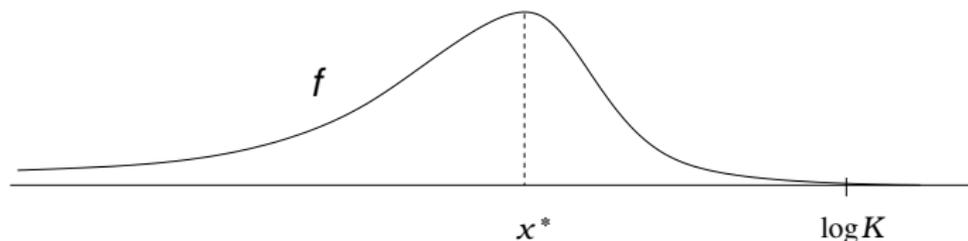
$$E_P e^{-rT} (K - e^{X_T})^+ \mathbf{1}_{\{T < \infty\}}.$$

**Idea:**

Find  $M$  and  $f$  with  $E_P e^{-rT} (K - e^{X_T})^+ \mathbf{1}_{\{T < \infty\}} = E_P f(X_T) M_T \mathbf{1}_{\{T < \infty\}}$ ,  
where  $f$  has a unique maximum at  $x^*$ .

Then

$$T^* = \min\{t \geq 0 \mid X_t = x^*\} \quad \text{if } E_P M_{T^*} = 1.$$



Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

How to find  $M_t$  ?

It holds for all  $\alpha \in \mathbb{R}$

$$(K - e^{X_T})^+ e^{-rT} = (K - e^{X_T})^+ (e^{X_T})^{-\alpha} (e^{X_T})^{\alpha} e^{-rT}.$$

Choose  $f(x) = (K - e^{x_T})^+ e^{-\alpha x}$  and  $\alpha$  such that  $M_t = e^{\alpha X_t} e^{-rt}$  is a martingale.

This holds when

$$\begin{aligned} M_t &= \exp [\alpha(\sigma B_t) + t(\alpha\mu - r)] \\ &= \exp [(\alpha\sigma)B_t - t(\alpha\sigma)^2/2]. \end{aligned}$$

$M_t$  is a positive martingale with  $M_0 = 1$  iff  $(\alpha\sigma)^2/2 + \alpha\mu - r = 0$

$\alpha^{\pm} = -\frac{\mu}{\sigma^2} \pm \sqrt{\frac{\mu^2}{\sigma^4} + \frac{2r}{\sigma^2}}$  are the two possible solutions.

Thus we have two martingales  $M_t^{\pm}$ .

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

Then we have

$$E_P e^{-rT} (K - e^{X_T})^+ \mathbf{1}_{\{T < \infty\}} = E_Q f(X_T) \mathbf{1}_{\{T < \infty\}}$$

$$\text{with } f(x) = \frac{(K - e^x)^+}{e^{\alpha^- x}} \text{ and } \frac{dQ_t}{dP_t} = M_t^-.$$

Let  $K < 1 + (-\alpha^-)^{-1}$ . Then  $f$  has a unique maximum at

$x^* = \log \frac{\alpha^- K}{\alpha^- - 1} < 0$ . Under  $Q$   $X$  is a Brownian motion with drift

$$\alpha^- \sigma^2 + \mu = -\sigma^2 \sqrt{\frac{\mu^2}{\sigma^4} + \frac{2r}{\sigma^2}} < 0.$$

This yields  $Q(T^* < \infty) = 1$  for  $T^* = \inf\{t > 0 \mid X_t = x^*\}$ .

Then

$$\sup_T E_P (e^{-rT} (K - e^{X_T})^+ \mathbf{1}_{\{T < \infty\}}) = E_Q f(X_{T^*}) = \frac{(K - e^{x^*})}{e^{\alpha^- x^*}}.$$

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

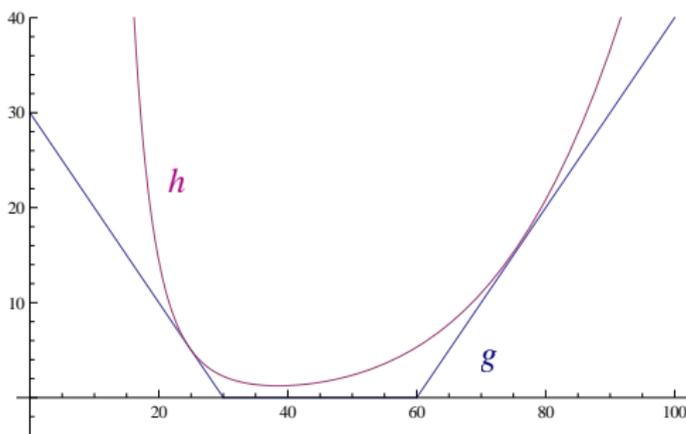
# Example: Strangle Option

$$g(x) = (e^x - K)^+ \vee (L - e^x)^+$$

$$h(x) = p^* e^{\alpha_1 x} + (1 - p^*) e^{\alpha_2 x} \text{ with}$$

$$0 < p^* < 1, \alpha_2 < 0 < \alpha_1$$

Here  $h$  is convex.



Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

**Put Option**

Two-Sided  
Boundaries

Stopping of  
Diffusions

# Two-Sided Boundaries

Let  $g$  be measurable,  $X_t = \sigma B_t + \mu t$  a Brownian motion with drift  $\mu$ , variance  $\sigma^2$  and  $X_0 = x$ . Find a stopping time  $T^*$  which maximizes

$$Ee^{-rT} g(X_T) 1_{\{T < \infty\}}.$$

$$\text{Let } \alpha_{1,2} = -\frac{\mu}{\sigma^2} \pm \sqrt{\frac{\mu^2}{\sigma^4} + \frac{2r}{\sigma^2}} \quad (\alpha_2 < 0 < \alpha_1).$$

Then  $M_t^{(i)} = e^{-rt} e^{\alpha_i X_t}$ ,  $i = 1, 2$  are positive martingales.

We consider boundaries of the type

- 1.)  $g(x) = x^2$
- 2.)  $g(x) = \max\{(L - e^x)^+, (e^x - K)^+\}$

Let  $p \in [0, 1]$ . Let  $M_t = pM_t^{(1)} + (1-p)M_t^{(2)}$ . Then

$$E_x e^{-rT} g(X_t) = E_x M_T \frac{g(X_T)}{pe^{\alpha_1 X_T} + (1-p)e^{\alpha_2 X_T}}.$$

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

Let  $g(x)$  be nonnegative and measurable with

$$\text{a) } 0 < \sup_{x \geq 0} (e^{-\alpha_1 x} g(x)) < \sup_{x \leq 0} (e^{-\alpha_1 x} g(x)) < \infty$$

$$\text{b) } 0 < \sup_{x \leq 0} (e^{-\alpha_2 x} g(x)) < \sup_{x \geq 0} (e^{-\alpha_2 x} g(x)) < \infty.$$

## Lemma

If a) and b) holds, there exists a  $p^* \in (0, 1)$  with  $\sup_{x \geq 0} G_{p^*}(x) = \sup_{x \leq 0} G_{p^*}(x)$ ,

where

$$G_p(x) = \frac{g(x)}{pe^{\alpha_1 x} + (1-p)e^{\alpha_2 x}}.$$

## Theorem

Let  $C^* = \sup_{x \in \mathbb{R}} G_{p^*}(x)$ . If there exists points  $x_1 > 0$  and  $x_2 < 0$  with

$G_{p^*}(x_1) = C^* = G_{p^*}(x_2)$ , then with  $T^* = \inf\{t > 0 \mid X_t = x_1 \text{ or } X_t = x_2\}$

$$\sup_T E_x e^{-rT} g(X_T) = E_x e^{-rT^*} g(X_{T^*}) = C^* (p e^{\alpha_1 x} + (1-p) e^{\alpha_2 x})$$

for  $x_1 \leq x \leq x_2$ .

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# Stopping of Diffusions with Random Exponential Discounting

$X$  a regular diffusion with  $X_0 = x$  and  $dX_t = \mu(X_t)dt + \sigma(X_t)dB_t$   
and  $B$  standard Brownian motion, state space  $I$ .

$g : \mathbb{R} \rightarrow \mathbb{R}_+$  a continuous function.

Find a stopping time  $T^*$  of  $X$  with

$$E_x \left( e^{-A(T)} g(X_T) 1_{\{T < \infty\}} \right) = \max.$$

$A(s)$ : additive continuous stochastic process adapted to  $\mathcal{F}^X$

$$A(s+t) = A(s) + A(t) \circ \theta_s$$

**Example:**

$$E_x \left( \exp \left\{ -r \int_0^T B_t^2 dt \right\} (B_T^+)^{\alpha} 1_{\{T < \infty\}} \right) = \max$$

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# The Main Idea Again

How to solve

$$V_*(x) = \sup_T E_x \left( e^{-A(T)} g(X_T) \mathbf{1}_{\{T < \infty\}} \right) ?$$

Let  $h : I \rightarrow \mathbb{R}_+$  be such that  $e^{-A(t)} h(X_t)$  is a positive local martingale and  $\sup_x \frac{g}{h}(x) = C^* < \infty$ . Then

$$\begin{aligned} E_x \left( e^{-A(T)} g(X_T) \mathbf{1}_{\{T < \infty\}} \right) &= E_x \left( e^{-A(T)} h(X_T) \frac{g(X_T)}{h(X_T)} \mathbf{1}_{\{T < \infty\}} \right) \\ &\leq C^* E_x \left( e^{-A(T)} h(X_T) \mathbf{1}_{\{T < \infty\}} \right) \\ &\leq C^* h(x). \end{aligned}$$

If there exists a  $T^*$  with  $\frac{g}{h}(X_{T^*}) = C^*$  and

$E_x \left( e^{-A(T^*)} h(X_{T^*}) \mathbf{1}_{\{T^* < \infty\}} \right) = h(x)$  the inequalities become equalities and the stopping problem has been solved.

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

## How to choose the Martingales?

$$\psi_+(x) = \begin{cases} E_x \left( e^{-A(\tau_{x_0})} \mathbf{1}_{\{\tau_{x_0} < \infty\}} \right) & \text{for } x \leq x_0 \\ \left[ E_{x_0} \left( e^{-A(\tau_x)} \mathbf{1}_{\{\tau_x < \infty\}} \right) \right]^{-1} & \text{for } x \geq x_0 \end{cases}$$
$$\psi_-(x) = \begin{cases} \left[ E_{x_0} \left( e^{-A(\tau_x)} \mathbf{1}_{\{\tau_x < \infty\}} \right) \right]^{-1} & \text{for } x \leq x_0 \\ E_x \left( e^{-A(\tau_{x_0})} \mathbf{1}_{\{\tau_{x_0} < \infty\}} \right) & \text{for } x \geq x_0. \end{cases}$$

$$M_t^{(+)} = e^{-A(t)} \psi_+(X_t) \quad \text{for } b \geq x \text{ on } 0 \leq t \leq \tau_b$$
$$M_t^{(-)} = e^{-A(t)} \psi_-(X_t) \quad \text{for } x \geq a \text{ on } 0 \leq t \leq \tau_a.$$

are u.i. martingales

with

$$E_x \left( M_{\tau_b}^{(+)} \mathbf{1}_{\{\tau_b < \infty\}} \right) = \psi_+(x) \quad \text{for } x \leq b$$
$$E_x \left( M_{\tau_a}^{(-)} \mathbf{1}_{\{\tau_a < \infty\}} \right) = \psi_-(x) \quad \text{for } x \geq a.$$

### Note:

If  $A(t) = \int_0^t r(X_s) ds$  with  $r(x) \geq 0$ , then  $\psi_{\pm}(x)$  are the solutions of

$\mathcal{D}\psi = r \cdot \psi$  with

$$\mathcal{D} = \mu(x) \frac{\partial}{\partial x} + \frac{1}{2} \sigma(x) \frac{\partial^2}{\partial x^2}.$$

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

### Example:

$$r(x) = rx^2 \text{ with } r > 0, x \geq 0.$$

$$\text{Let } \Psi(x) = e^{-x^2/2} \frac{2^{5/4}}{\Gamma(1/2)} \int_0^\infty e^{xt-t^2/2} \frac{1}{\sqrt{t}} dt$$

Then  $\psi(x) = \Psi(\sqrt[4]{8r}x)$  is an increasing solution of

$$\frac{1}{2}\psi''(x) = rx^2\psi(x) \quad \text{with } \psi(0) = 1.$$

Then  $\exp\left(-r \int_0^t X_s^2 ds\right) \psi(X_t)$  is a local martingale and by the OST

$$E_x \exp\left(-r \int_0^{\tau_0} X_s^2 ds\right) = \psi(x) \quad \text{for } x \leq 0$$

and

$$E_0 \exp\left(-r \int_0^{\tau_x} X_s^2 ds\right) = \psi(x)^{-1} \quad \text{for } x \geq 0.$$

Thus  $\psi(x) = \psi_+(x)$ .

$$\text{Then } \sup_{x \in \mathbb{R}} [(x^+)^{\alpha} / \psi_+(x)] = \sup_{x \geq 0} [(x^+)^{\alpha} / \psi_+(x)] < \infty.$$

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

$$\begin{aligned} \text{Thus } E_x \exp(-A(T))(B_T^+)^{\alpha} \mathbb{1}_{\{T < \infty\}} &= E_x \frac{e^{-A(T)} \psi_+(B_T) (B_T^+)^{\alpha}}{\psi_+(B_T)} \\ &\leq \psi_+(x) \frac{(x^*)^{\alpha}}{\psi_+(x^*)} \end{aligned}$$

With  $x^* = \arg \max_x [(x^+)^{\alpha} / \psi_+(x)] > 0$  one has  $T^* = \inf\{t > 0 \mid X_t = x^*\}$ .

Is  $S^* = [x^*, \infty)$  the optimal stopping set?

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

$$\begin{aligned} \text{Thus } E_x \exp(-A(T))(B_T^+)^{\alpha} \mathbb{1}_{\{T < \infty\}} &= E_x \frac{e^{-A(T)} \psi_+(B_T) (B_T^+)^{\alpha}}{\psi_+(B_T)} \\ &\leq \psi_+(x) \frac{(x^*)^{\alpha}}{\psi_+(x^*)} \end{aligned}$$

With  $x^* = \arg \max_x [(x^+)^{\alpha} / \psi_+(x)] > 0$  one has  $T^* = \inf\{t > 0 \mid X_t = x^*\}$ .

Is  $S^* = [x^*, \infty)$  the optimal stopping set?

What is  $v(x)$ ?

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

$$\begin{aligned} \text{Thus } E_x \exp(-A(T))(B_T^+)^{\alpha} \mathbb{1}_{\{T < \infty\}} &= E_x \frac{e^{-A(T)} \psi_+(B_T)(B_T^+)^{\alpha}}{\psi_+(B_T)} \\ &\leq \psi_+(x) \frac{(x^*)^{\alpha}}{\psi_+(x^*)} \end{aligned}$$

With  $x^* = \arg \max_x [(x^+)^{\alpha} / \psi_+(x)] > 0$  one has  $T^* = \inf\{t > 0 \mid X_t = x^*\}$ .

Is  $S^* = [x^*, \infty)$  the optimal stopping set?

What is  $v(x)$ ?

$$v(x) = \begin{cases} \frac{(x^*)^{\alpha}}{\Psi(\sqrt[4]{8r} x^*)} \Psi(\sqrt[4]{8r} x) & \text{for } x \leq x^*, \\ x^{\alpha}, & \text{for } x \geq x^*. \end{cases}$$

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

# Characterization of the Stopping Set

For  $r(x) = r$  a complete characterization of the stopping set has been given by Søren Christensen in his dissertation (2010). He showed by using a Choquet-representation result for  $r$ -harmonic functions that the optimal stopping set  $S^*$  can be characterized as

$$S^* = \left\{ x \mid \exists r\text{-harmonic } h \text{ with } x = \arg \max_y \frac{g(y)}{h(y)} \right\}.$$

It implies that the value function is the minimum of  $r$ -harmonic functions  $\geq g$ .

This result has been extended by Cedric Thoms to random discounting.

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

Let  $v(x) = \sup_T E_x(e^{-A(T)} g(X_T) 1_{\{T < \infty\}})$  and let an optimal  $T^*$  exist.

Let  $S^* = \{x \mid v(x) = g(x)\}$ , then  $\tau^* = \inf\{t > 0 \mid X_t \in S^*\}$  is optimal and  $P_x(\tau^* \leq T^*) = 1$  for all  $x \in I$ .

Define: A nonnegative function  $f : I \rightarrow [0, \infty)$  is  $A$ -harmonic if it holds

$$E_x \left[ e^{-A(\tau(c,d))} f(X_{\tau(c,d)}) \right] = f(x)$$

for all  $(c, d) \subset I$  and for all  $x \in I$ .

## Theorem (Christensen–Irlle, Thoms)

*A point  $x \in I$  is in  $S^* = \{v = g\}$  if and only if an  $A$ -harmonic function  $h$  exists (i.e.  $h = \alpha\psi_+ + \beta\psi_-$ , and  $\alpha, \beta \geq 0$  and  $\alpha + \beta > 0$ ), such that*

$$x = \arg \max_y \frac{g(y)}{h(y)}.$$

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

## Corollary

Let  $g$ ,  $\psi_+$  and  $\psi_-$  be continuously differentiable. Let  $X \in S^*$  with

$\frac{g(x)}{h(x)} = 1$  and let  $w(x) = \psi'_+(x)\psi_-(x) - \psi_+(x)\psi'_-(x) \neq 0$ , then

$$\alpha = \alpha(x) = \frac{g(x)\psi'_+(x) - g'(x)\psi_+(x)}{w(x)}$$

and 
$$\beta = \beta(x) = \frac{g'(x)\psi_-(x) - g(x)\psi'_-(x)}{w(x)}.$$

## Remark

Using this Corollary one can show that  $S^* = [x^*, \infty)$  in the example.

Testing the Sign of  
the Drift of BM

RST

The Disruption  
Problem

Parking Problem

GPP

Generalized Parking  
Problem (GPP)

Testing the Mean  
sequentially

Basic Idea

Parabolic  
Boundaries

Put Option

Two-Sided  
Boundaries

Stopping of  
Diffusions

# Sequential Analysis

- Beibel, M. (1996). A note on Ritov's Bayes approach to the minimax property of the CUSUM procedure, *Annals of Statistics* **24**, 1804–1816
- Beibel, M. (1997). Sequential change-point detection in continuous time, when the post-change drift is unknown, *Bernoulli* **3**, 457–478
- Beibel, M.; Lerche, H. R. (2003). Sequential Bayes Detection of Trend Changes, in *Foundations of Statistical Inference*, Eds.: Y. Haitovsky, H. R. Lerche, Y. Ritov, Physika Verlag, 117–130
- Woodroffe, M.; Lerche, H. R.; Keener, R. (1994). *A Generalized Parking Problem, Statistical Decision Theory and Related Topics V*, Eds.: S. S. Gupta, J. O. Berger, Springer Verlag, 523–532
- Keener, R.; Lerche, H. R.; Woodroffe M. (1995). A Nonlinear Parking Problem, *Sequential Analysis* **14**, 247–272

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

- Lerche, H. R. (1986). An Optimal Property of the Repeated Significance Test, *PNAS USA* **83**, 1546–1548
- Lorden, G. (1977). Nearly-optimal sequential tests for finitely many parameter values, *Annals of Statistics* **5**, 1–21
- Schwarz, G. (1993). *Tests mit Macht 1 und Bayes-Optimalität*, Verlag Shaker, Aachen
- Siegmund, D. (1985). *Sequential Analysis: Tests and Confidence Intervals*. Springer-Verlag
- Shiryaev, A. N. (1963). On optimum methods in quickest detection problems. *Theory Probab. Appl.* **8**, 22–46
- Wald, A.; Wolfowitz, J. (1950). Bayesian solutions of sequential problems. *Ann. Math. Statist.* **21**, 82–99

# Optimal Stopping

- Chow, Y. S.; Robbins, H; Siegmund, D. (1971). *Great Expectations: The Theory of Optimal Stopping*, Houghton Mifflin, Boston
- Beibel, M.; Lerche, H. R. (1997). A New Look at Optimal Stopping Problems related to Mathematical Finance, *Statistica Sinica* **7**, 93–108
- Beibel, M.; Lerche, H. R. (2000). Optimal Stopping of Regular Diffusions under Random Discounting, *Theory Probab. Appl.* **45**, 657–669
- Christensen, S.; Irle A. (2011). A harmonic function technique for the optimal stopping of diffusion, *Stochastics* **83**, 347–363
- Lerche, H. R.; Urusov, M. (2007). Optimal Stopping via Measure Transformation: The Beibel–Lerche approach, *Stochastics* **79**, 275–291
- Lerche, H. R.; Urusov, M. (2010). On Minimax Duality in Optimal Stopping, *Sequential Analysis* **29**, 328–342
- Peskir, G.; Shiryaev, A. (2006). *Optimal Stopping and Free-Boundary Problems*, Birkhäuser Verlag
- Thoms, C. (2012). *Optimales Stoppen bei zufälliger Diskontierung*, Diplomarbeit, Freiburg.

Testing the Sign of the Drift of BM

RST

The Disruption Problem

Parking Problem

GPP

Generalized Parking Problem (GPP)

Testing the Mean sequentially

Basic Idea

Parabolic Boundaries

Put Option

Two-Sided Boundaries

Stopping of Diffusions

Thank you for your attention!

